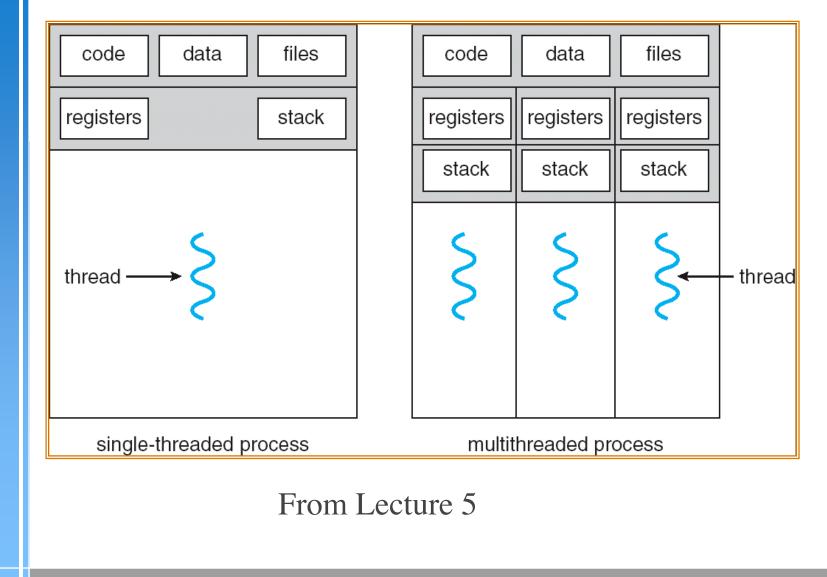
#### So far....

- Firmware identifies hardware devices present
- OS bootstrap process: uses the list created by firmware and loads driver modules for each detected hardware. Initializes internal data structures (PCB, device queue for each device)
- Each process can have one or more threads
- Processes can be in Wait (for resources), Ready (waiting for processor) and Run states.
- Next: scheduling next process from Wait to Run

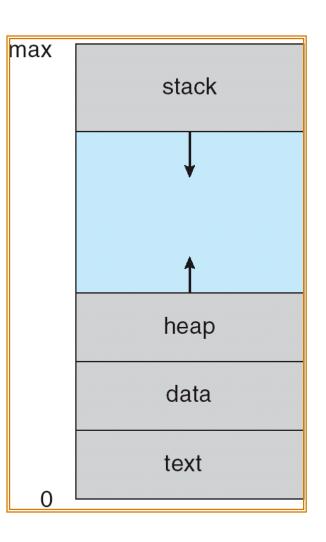
## Clarification re: multi-threaded process



1/31/08

#### From Lecture 4

- Local variables are stored in stack
- Malloc() memory is stored in heap
- Compilers create and manage these locations.
  They request a certain amount of stack during program loading from the OS
  - The specific format depends on the program structure (e.g. ELF)



## Scheduling basics

CPU–I/O Burst Cycle – Process execution consists of a cycle of CPU execution and I/O wait

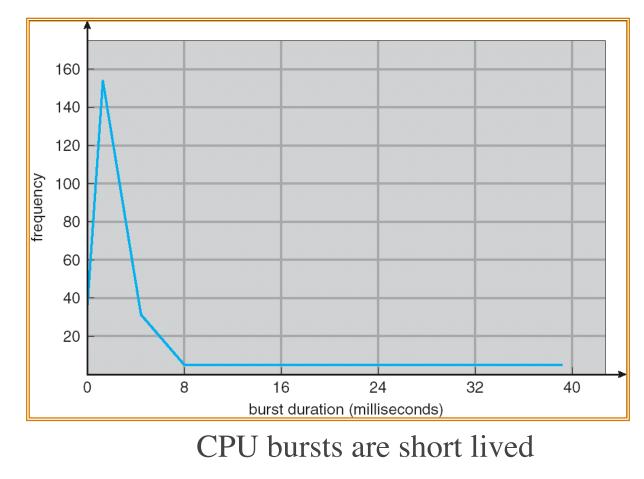
•	_
load store add store read from file	} CPU burst
wait for I/O	≻ I/O burst
store increment index write to file	CPU burst
wait for I/O	} I/O burst
load store add store read from file	CPU burst
wait for I/O	≻ I/O burst
•	ر

 CPU scheduling depends on the observation that processes cycle between CPU execution and I/O wait.

1/31/08

# Histogram of CPU-burst Times

#### Typical CPU-burst duration



1/31/08

CSE 30341: Operating Systems Principles

## **CPU Scheduler**

- Selects from among the processes in memory that are ready to execute, and allocates the CPU to one of them
- CPU scheduling decisions may take place when a process:
  - 1. Switches from running to waiting state (e.g. I/O request)
  - 2. Switches from running to ready state (e.g. Interrupt)
  - 3. Switches from waiting to ready (e.g. I/O completion)
  - 4. Terminates
- Scheduling under 1 and 4 is non-preemptive (cooperative)
- All other scheduling is *preemptive* have to deal with possibility that operations (system calls) may be incomplete

## Dispatcher

- Dispatcher module gives control of the CPU to the process selected by the short-term scheduler; this involves:
  - switching context
  - switching to user mode
  - jumping to the proper location in the user program to restart that program
- Dispatch latency time it takes for the dispatcher to stop one process and start another running
  - Should be as low as possible

## Scheduling Criteria

- CPU utilization (max) keep the CPU as busy as possible
- Throughput (max) # of processes that complete their execution per time unit
- Turnaround time (min) amount of time to execute a particular process
- Waiting time (min) amount of time a process has been waiting in the ready queue
- Response time (min) amount of time it takes from when a request was submitted until the first response is produced, not output (for time-sharing environment)
- In typical OS, we optimize each to various degrees depending on what we are optimizing the OS



## **Optimization criteria**

- Max CPU utilization
- Max throughput
- Min turnaround time
- Min waiting time
- Min response time
- Analysis using Gantt chart (illustrates when processes complete)





## First-Come, First-Served (FCFS) Scheduling

Process	<u>Burst Time</u>
$P_1$	24
$P_2$	3
$P_{3}$	3

Suppose that the processes arrive in the order:  $P_1$ ,  $P_2$ ,  $P_3$ The Gantt Chart for the schedule is:

P <sub>1</sub>	P <sub>2</sub>	P <sub>3</sub>
) 2	4 2	7 30

- Waiting time for  $P_1 = 0$ ;  $P_2 = 24$ ;  $P_3 = 27$
- Average waiting time: (0 + 24 + 27)/3 = 17



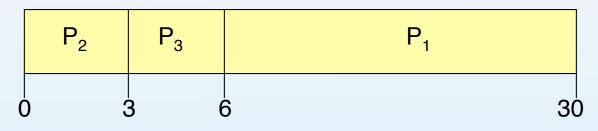


# FCFS Scheduling (Cont.)

Suppose that the processes arrive in the order

P2, P3, P1

The Gantt chart for the schedule is:



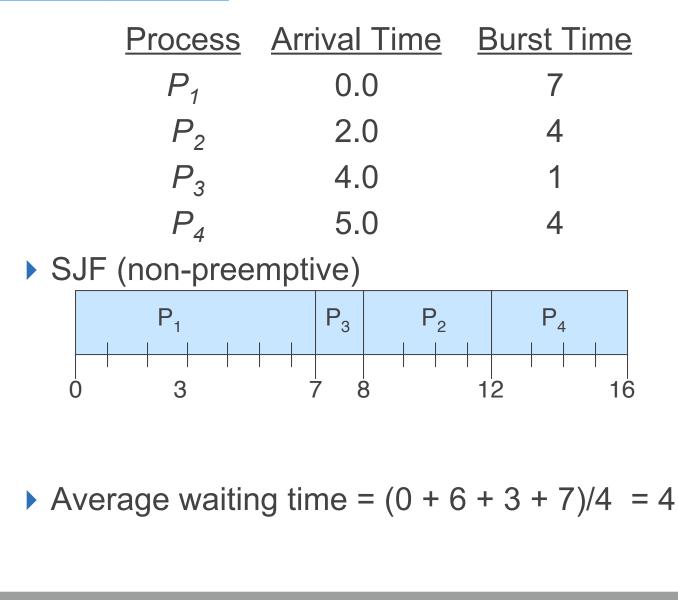
- Waiting time for P1 = 6; P2 = 0; P3 = 3
- Average waiting time: (6 + 0 + 3)/3 = 3
- Much better than previous case
- Convoy effect short process behind long process



## Shortest-Job-First (SJR) Scheduling

- Associate with each process the length of its next CPU burst. Use these lengths to schedule the process with the shortest time
- Two schemes:
  - nonpreemptive once CPU given to the process, it cannot be preempted until completes its CPU burst
  - preemptive if a new process arrives with CPU burst length less than remaining time of current executing process, preempt. This scheme is know as the Shortest-Remaining-Time-First (SRTF)
- SJF is optimal gives minimum average waiting time for a given set of processes

#### **Example of Non-Preemptive SJF**



## Example of Preemptive SJF

	Proce	<u>ess</u> <u>A</u>	rrival Time	<u>Burst Time</u>
	$P_1$		0.0	7
	$P_2$	2	2.0	4
	$P_3$	}	4.0	1
	$P_4$		5.0	4
► SJF	(preer	nptive	)	
P <sub>1</sub> F	$P_2 P_3$	P <sub>2</sub>	P <sub>4</sub>	P <sub>1</sub>
0 2	4	5	7 11	16

Average waiting time = (9 + 1 + 0 + 2)/4 = 3