# Checkpoints

- Logs keep growing. After every failure, we'd have to go back and replay the log. This can be time consuming.
- Checkpoint frequently
  - Output all log records currently in volatile storage onto stable storage
  - Output all modified data residing in volatile storage to the stable storage
  - Output a log record <checkpoint> into stable storage
- On failure, search backwards till we hit the first checkpoint. The first transaction start from the checkpoint (going back) is the start of replay



# Serializability

- Transactions can be concurrent. Such concurrency may cause problems depending on the interleaving of the transactions. We introduce stricter notions of this phenomenon in order to predict system behavior
- Schedule is an execution sequence
- Serial schedule: Schedule where two concurrent transactions follow one after the other
  - For two transactions T1, T2: serial schedule is T1 then T2 or T2 then T1. For n transactions, we have n! choices, all of which is valid
  - Serial schedule cannot fully utilize the system resources and so we want to relax the schedule: non-serial schedule



#### Conflict

- We define a schedule to be in conflict if they both operate on the same data item and one of the operations is a write
- If there is no conflict, the schedule can be swapped.
- If after non-conflicting swaps we reach a serial schedule, then that schedule is called conflict serializable



Read(A) Read(A) Write(A) Write(A) read(A) Read(B) write(A) Write(B) Read(B) read(A) Write(B) write(A) read(B) read(B) write(B) write(B) Conflict serializable Serial schedule



schedule

# Locking protocol to enforce order

- Shared: Transaction can read but not write
- Exclusive: Transaction can read and write
- Two phase protocol to ensure serializability:
  - Growing phase transaction can obtain but not release locks
  - Shrinking phase transaction can release lock but not acquire new ones
  - Ensures conflict serializability not is not free from deadlocks



### Timestamp-based Protocols

- ▶ Timestamp transactions: Can be real wall clock time or logical clock
- ▶ The timestamp determines the serializability order
- ▶ For each data item (Q), associate two timestamps
  - W-timestamp denotes largest timestamp of any transaction that successfully executed write(Q).
  - R-timestamp for read(Q)
- Suppose Ti issues read(Q):
  - If TS(Ti) < W-timestamp(Q), rollback Ti</p>
  - If TS(Ti) >= W-timestamp(Q), execute Ti, R-timestamp = maximum (R-timestamp(Q) and TS(Ti))
- Similarly for Ti issuing write(Q):



### Chapter 7: Deadlocks

- ▶ To develop a description of deadlocks, which prevent sets of concurrent processes from completing their tasks
- ➤ To present a number of different methods for preventing or avoiding deadlocks in a computer system.



#### The Deadlock Problem

- A set of blocked processes each holding a resource and waiting to acquire a resource held by another process in the set.
- Example
  - System has 2 tape drives.
  - $Arr P_1$  and  $P_2$  each hold one tape drive and each needs another one.
- Example

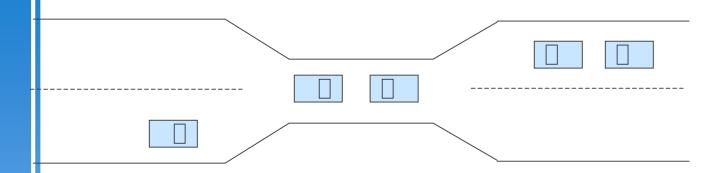
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semaphores A and B, initialized to 1

$P_0$	$P_1$
wait (A);	wait(B)
wait (B);	wait(A)



# Bridge Crossing Example



- Traffic only in one direction.
- Each section of a bridge can be viewed as a resource.
- If a deadlock occurs, it can be resolved if one car backs up (preempt resources and rollback).
- Several cars may have to be backed up if a deadlock occurs.
- Starvation is possible.



# System Model

- Resource types  $R_1, R_2, ..., R_m$ CPU cycles, memory space, I/O devices
- $\blacktriangleright$  Each resource type  $R_i$  has  $W_i$  instances.
- ▶ Each process utilizes a resource as follows:
  - request
  - use
  - release



#### **Deadlock Characterization**

Deadlock can arise if four conditions hold simultaneously.

- Mutual exclusion: only one process at a time can use a resource.
- ▶ Hold and wait: a process holding at least one resource is waiting to acquire additional resources held by other processes.
- No preemption: a resource can be released only voluntarily by the process holding it, after that process has completed its task.
- ▶ Circular wait: there exists a set  $\{P_0, P_1, ..., P_0\}$  of waiting processes such that  $P_0$  is waiting for a resource that is held by  $P_1, P_1$  is waiting for a resource that is held by

 $P_2, ..., P_{n-1}$  is waiting for a resource that is held by  $P_n$ , and  $P_0$  is waiting for a resource that is held by  $P_0$ .



# Resource-Allocation Graph

A set of vertices *V* and a set of edges *E*.

- V is partitioned into two types:
  - $P = \{P_1, P_2, ..., P_n\}$ , the set consisting of all the processes in the system.
  - $R = \{R_1, R_2, ..., R_m\}$ , the set consisting of all resource types in the system.
- ▶ request edge directed edge  $P_1 \rightarrow R_j$
- ▶ assignment edge directed edge  $R_j \rightarrow P_i$



### Resource-Allocation Graph (Cont.)

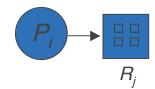
Process



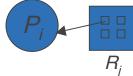
Resource Type with 4 instances



 $\triangleright$   $P_i$  requests instance of  $R_j$ 



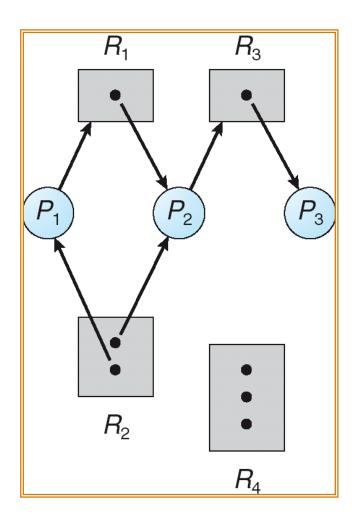
 $\triangleright$   $P_i$  is holding an instance of  $R_i$ 





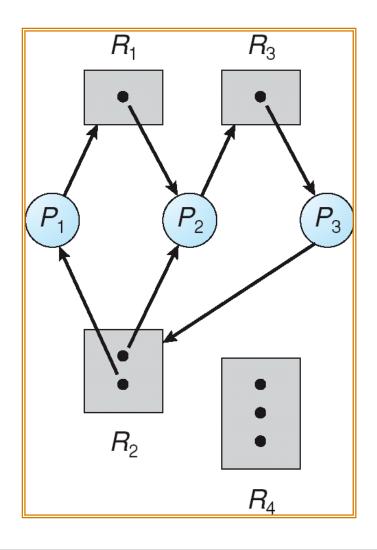
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#### Example of a Resource Allocation Graph





#### Resource Allocation Graph With A Deadlock





#### Resource Allocation Graph With A Cycle But No Deadlock

